

3.9 Forced Vibrations.

I) Forced Vibrations with Damping.

$$\boxed{m u'' + \gamma u' + k u = F_0 \cos \omega t} \quad (1.1)$$

Typical
External force.

General Soln:

- a) First find a fundamental set of Solns. for corresponding homogeneous equation:

$$\boxed{m u'' + \gamma u' + k u = 0} \quad (1.2)$$

Charact. polyn: $m r^2 + \gamma r + k = 0$

$$r_{1,2} = \frac{-\gamma \pm \sqrt{\gamma^2 - 4km}}{2m}$$

Three possibilities for r_1 and r_2

- i) r_1, r_2 real and $r_1 \neq r_2$

$$u_1 = e^{r_1 t}, \quad u_2 = e^{r_2 t}$$

- ii) $r_1 = r_2$ real $\Rightarrow u_1 = e^{r_1 t}, u_2 = t e^{r_1 t}$

- iii) $r_1 = \alpha + i\beta, r_2 = \alpha - i\beta, \beta \neq 0$

$$u_1 = e^{\alpha t} \cos \beta t, \quad u_2 = e^{\alpha t} \sin \beta t.$$

In all those cases:

If real, $r_1 < 0$, $r_2 < 0$ why?

If complex, $\alpha < 0$, why?

If $U_p(t)$ is a particular soln. of (1.1),
then its general soln:

$$U(t) = \underbrace{C_1 U_1(t) + C_2 U_2(t)}_{\substack{\text{General Soln. of} \\ \text{homog. equ.}}} + U_p(t) = U_h(t) + U_p(t)$$

From the previous consideration of the roots r_1 and r_2

$$U_h(t) \xrightarrow[t \rightarrow \infty]{} 0$$

then, $U(t) = U_h(t) + U_p(t) \xrightarrow[t \rightarrow \infty]{} U_p(t)$

$U_h(t)$ is called the transient soln. and

$U_p(t)$ is called the steady or forced response soln.

$U_h(t)$ depends on the ICs. The energy provided by them to the system is dissipated by the damping force.

For the particular form of the forcing function in (1.1)

$$F_0 \cos(\omega t),$$

it holds that

$$u_p(t) = A \cos(\omega t) + B \sin(\omega t)$$

or $u_p(t) = R \cos(\omega t - \delta).$

where

$$R = \frac{F_0}{\sqrt{m^2(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2}}$$

Notice that when ω is close to ω_0 and γ is small, the amplitude R is large even for small F_0 . This phenomenon is known as resonance.

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$$\begin{cases} u'' + 2b u' + \omega_0^2 u = F \cos(\omega t) \\ u(0) = 1, u'(0) = 1 \end{cases}$$

- i) Small b and $\omega < \omega_0$, or weak damping
- ii) larger b and $\omega < \omega_0$, or strong damping
- iii) small b and $\omega = \omega_0$ Resonance.

II) Forced Vibrations without Damping.

$$\boxed{u'' + \omega_0^2 u = F \cos(\omega t)} \quad (4.1)$$

Two Cases:

a) $\boxed{\omega \neq \omega_0}$

Charact. polyn: $r^2 + \omega_0^2 = 0 \Rightarrow r_{1,2} = \pm i \sqrt{\omega_0^2} = \pm i \omega_0$

then $u_h(t) = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t) \quad (4.2)$

Also $u_p(t) = A \cos(\omega t) + B \sin(\omega t) \quad (4.3)$

To determine A and B, we substitute (4.3) into (4.1).

$$u_p' = -A\omega \sin \omega t + B\omega \cos \omega t$$

$$u_p'' = -A\omega^2 \cos \omega t - B\omega^2 \sin \omega t$$

$$\omega_0^2 (u_p = A \cos \omega t + B \sin \omega t)$$

Then $u_p'' + \omega_0^2 u_p = A(\omega_0^2 - \omega^2) \cos \omega t + B(\omega_0^2 - \omega^2) \sin \omega t$

$$= F \cos \omega t$$

Thus,

$$A(\omega_0^2 - \omega^2) = F$$

$$B(\omega_0^2 - \omega^2) = 0 \Rightarrow B = 0$$

$$\Rightarrow \boxed{A = \frac{F}{\omega_0^2 - \omega^2}}$$

$$(4.2)$$

Therefore, general soln is

$$u(t) = C_1 \cos \omega_0 t + C_2 \sin \omega_0 t + \frac{F}{\omega_0^2 - \omega^2} \cos \omega t \quad (5.1)$$

C_1 and C_2 are determined using ICs.

after substituting (5.1) (homog. + particular solns) into (4.1).

Obviously, for ω close to ω_0 the solution becomes very large.

b) $\boxed{\omega = \omega_0}$

$$u(t) = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t) + At \cos(\omega_0 t) + Bt \sin(\omega_0 t) \quad (5.2)$$

Substitution into (4.1) leads to

$$u(t) = C_1 \cos \omega_0 t + C_2 \sin \omega_0 t + \frac{F_0}{2\omega_0} t \sin \omega_0 t \quad (5.3).$$

Show this!

A Beat Soln:

Consider

$$\begin{cases} u'' + \omega_0^2 u = F \cos \omega t \\ u(0) = 0, u'(0) = 0 \end{cases}$$

The general soln. is given by (5.1)

$$u(t) = C_1 \cos \omega_0 t + C_2 \sin \omega_0 t + \frac{F}{\omega_0^2 - \omega^2} \cos \omega t$$

Using ICs:

$$C_1 = \frac{-F}{(\omega_0^2 - \omega^2)}, \quad C_2 = 0$$

Then,

$$u(t) = \frac{F}{(\omega_0^2 - \omega^2)} (\cos \omega t - \cos \omega_0 t)$$

$$\text{If } A = \frac{(\omega_0 + \omega)t}{2}, \quad B = \frac{(\omega_0 - \omega)t}{2}$$

$$\text{then } \cos(\omega_0 t) = \cos(A - B) = \cos A \cos B + \sin A \sin B.$$

$$\cos(\omega t) = \cos(A + B) = \cos A \cos B - \sin A \sin B$$

$$\Rightarrow \cos(\omega_0 t) - \cos(\omega t) = 2 \sin A \sin B = 2 \sin\left(\frac{\omega_0 + \omega}{2} t\right) \sin\left(\frac{\omega_0 - \omega}{2} t\right)$$

Thus,

$$u(t) = \left[\frac{2F}{\omega_0^2 - \omega^2} \sin\left(\frac{\omega_0 + \omega}{2} t\right) \right] \sin\left(\frac{\omega_0 - \omega}{2} t\right)$$