

7.6 Complex Eigenvalues

Let us begin with an example

$$\vec{X}'(t) = \begin{pmatrix} -1 & 9 \\ -1 & -1 \end{pmatrix} \vec{X} = A \vec{X}, \quad A = \begin{pmatrix} -1 & 9 \\ -1 & -1 \end{pmatrix} \quad (1.1)$$

Again, we look for solutions in the form:

$$\vec{X}(t) = \vec{\xi} e^{rt} \quad (1.2)$$

$$\text{Therefore, } \cancel{\vec{\xi}} r e^{rt} = \begin{pmatrix} -1 & 9 \\ -1 & -1 \end{pmatrix} \cancel{\vec{\xi}} e^{rt}$$

$$\text{or } \begin{pmatrix} -1 & 9 \\ -1 & -1 \end{pmatrix} \vec{\xi} - r \vec{\xi} = 0$$

$$\text{or } \begin{pmatrix} -1 & 9 \\ -1 & -1 \end{pmatrix} \vec{\xi} - r I \vec{\xi} = 0$$

$$\text{or } \begin{pmatrix} -1-r & 9 \\ -1 & -1-r \end{pmatrix} \vec{\xi} = 0 \Leftrightarrow (A - rI) \vec{\xi} = 0$$

For non-trivial solutions

$$|A - rI| = 0 \Leftrightarrow (-1-r)(-1-r) + 9 = 0$$

$$(r+1)^2 + 9 = 0 \Leftrightarrow r^2 + 2r + 10 = 0$$

$$\text{Then, } r = \frac{-2 \pm \sqrt{4-40}}{2} = -1 \pm \frac{\sqrt{-36}}{2} i = -1 \pm 3i$$

So eigenvalues are $r_1 = -1 + 3i$
 $r_2 = -1 - 3i$

Eigenvectors for $\boxed{r_1 = -1 + 3i}$

are obtained by solving

$$\begin{pmatrix} -1 - (-1 + 3i) & 9 \\ -1 & -1 - (-1 + 3i) \end{pmatrix} \begin{pmatrix} \xi_1^{(1)} \\ \xi_2^{(1)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\text{or } \begin{pmatrix} -3i & 9 \\ -1 & -3i \end{pmatrix} \begin{pmatrix} \xi_1^{(1)} \\ \xi_2^{(1)} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

So we arrive to the system of equations

$$\begin{cases} -3i \xi_1^{(1)} + 9 \xi_2^{(1)} = 0 & (2.1) \end{cases}$$

$$\begin{cases} -\xi_1^{(1)} - 3i \xi_2^{(1)} = 0 & (2.2) \end{cases}$$

Clearly, equ. (2.1) is a multiple of equ. (2.2). In fact,

$$3i (\text{Equ. 2}) = \text{Equ. (2.1)}$$

This is expected. Otherwise, it would not have non-trivial solutions.

Then, solutions of system (2.1)-(2.2)
are

$$\xi_1^{(1)} = -3i \xi_2^{(1)}$$

or
$$\vec{\xi}^{(1)} = e \begin{pmatrix} -3i \\ 1 \end{pmatrix}$$

And a complex solution of (1.1) given by (1.2)
is

$$\begin{aligned} \vec{X}^{(1)}(t) &= e^{(-1+3i)t} \begin{pmatrix} -3i \\ 1 \end{pmatrix} \\ &= e^{-t} e^{3it} \begin{pmatrix} -3i \\ 1 \end{pmatrix} \\ &= e^{-t} (\cos 3t + i \sin 3t) \begin{pmatrix} -3i \\ 1 \end{pmatrix} \\ &= e^{-t} \begin{pmatrix} +3 \sin 3t - i 3 \cos 3t \\ \cos 3t + i \sin 3t \end{pmatrix} \\ &= \begin{pmatrix} 3e^{-t} \sin 3t - i 3e^{-t} \cos 3t \\ e^{-t} \cos 3t + i e^{-t} \sin 3t \end{pmatrix} \\ &= \begin{pmatrix} 3e^{-t} \sin 3t \\ e^{-t} \cos 3t \end{pmatrix} + i \begin{pmatrix} -3e^{-t} \cos 3t \\ e^{-t} \sin 3t \end{pmatrix} \\ &= \vec{u}(t) + i \vec{v}(t) \end{aligned}$$

We can easily show that $u(t)$ and $v(t)$ are solutions of (1.1). 4

$\nearrow$ real part of $\tilde{x}$ $\nearrow$ Imaginary part of $\tilde{x}$

Thm 7.4.5

Consider $\tilde{x}'(t) = A \tilde{x}(t)$, A $n \times n$ matrix (4.1) of real entries

$$\text{If } \tilde{x}(t) = \vec{u}(t) + i\vec{v}(t) \quad (4.2)$$

is a complex-valued solution of the above system then its real part $\vec{u}(t)$ and its imaginary part $\vec{v}(t)$ are also solutions of this system.

Proof.

Subst. (4.2) into (4.1)

$$(\vec{u}(t) + i\vec{v}(t))' = A(\vec{u}(t) + i\vec{v}(t))$$

$$\Rightarrow (\vec{u}'(t) - A\vec{u}(t)) + i(\vec{v}'(t) - A\vec{v}(t)) = \vec{0}$$

$$\Rightarrow \vec{u}'(t) - A\vec{u}(t) = 0 \Rightarrow \boxed{\vec{u}'(t) = A\vec{u}(t)} \checkmark$$

$$\text{and } \vec{v}'(t) - A\vec{v}(t) = 0 \Rightarrow \boxed{\vec{v}'(t) = A\vec{v}(t)}$$

7.6 Complex eigenvalues. (cont.)

If eigenvalues are pure imaginary numbers:

$\lambda_1 = i\beta$, $\lambda_2 = -i\beta$, then the equilibrium point $\vec{x} = \vec{0}$ is called a center.

$$\vec{x}'(t) = \begin{pmatrix} 3 & 2 \\ -5 & -3 \end{pmatrix} \vec{x}(t)$$

$$|A - \lambda I| = \begin{vmatrix} 3 - \lambda & 2 \\ -5 & -3 - \lambda \end{vmatrix} = \begin{vmatrix} -(\lambda - 3) & 2 \\ -5 & -(\lambda + 3) \end{vmatrix} = (\lambda - 3)(\lambda + 3) + 10$$

$$= \lambda^2 - 9 + 10 = \lambda^2 + 1 = 0$$

$$\Rightarrow \lambda_1 = i, \quad \lambda_2 = -i$$

⊕ Eigenvectors:

$$\lambda_1 = i \quad \begin{pmatrix} 3 - i & 2 \\ -5 & -3 - i \end{pmatrix} \begin{pmatrix} \xi_1' \\ \xi_2' \end{pmatrix} = \begin{pmatrix} (3 - i)\xi_1' + 2\xi_2' \\ -5\xi_1' + (-3 - i)\xi_2' \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{aligned} \sqrt{\cdot} \left[(3 - i)\xi_1' + 2\xi_2' = 0 \right] & \times \left(\frac{3+i}{2} \right) \text{ lin. dep.} \\ -5\xi_1' - (3+i)\xi_2' = 0 & \leftarrow \end{aligned}$$

(6)

Solving the first equ. for ξ_2' :

$$\xi_2' = -\frac{3-i}{2} \xi_1'$$

$$\Rightarrow \vec{\xi}^{(1)} = \begin{pmatrix} 2 \\ -3+i \end{pmatrix}$$

$\Rightarrow$ Complex solution:

$$Z^{(1)}(t) = e^{it} \begin{pmatrix} 2 \\ -3+i \end{pmatrix} = \begin{pmatrix} 2\cos t + 2i\sin t \\ (-3+i)(\cos t + i\sin t) \end{pmatrix} =$$

$$= \begin{pmatrix} 2\cos t + 2i\sin t \\ -3\cos t - \sin t + i(\cos t - 3\sin t) \end{pmatrix} =$$

$$= \begin{pmatrix} 2\cos t \\ -3\cos t - \sin t \end{pmatrix} + i \begin{pmatrix} 2\sin t \\ \cos t - 3\sin t \end{pmatrix} = U(t) + iV(t)$$

$U(t)$, and $V(t)$ are real solns and they are l. indep.

In fact,

$$\begin{vmatrix} 2\cos t & 2\sin t \\ -3\cos t - \sin t & \cos t - 3\sin t \end{vmatrix} = 2\cos^2 t - 6\cancel{\cos t \sin t} + 6\cancel{\sin t \cos t} + 2\sin^2 t = 2 \neq 0.$$

therefore, General Soln.:

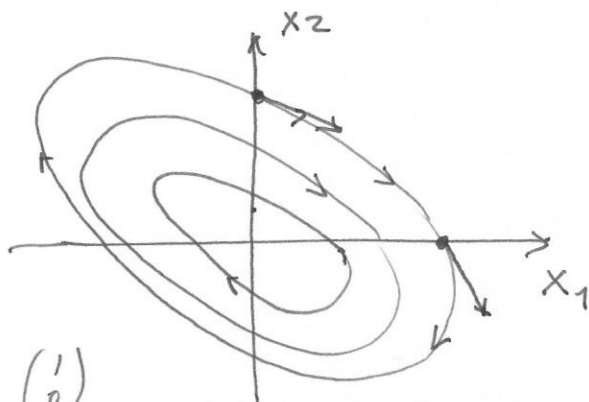
$$\vec{X}(t) = C_1 \begin{pmatrix} 2\cos t \\ -3\cos t - \sin t \end{pmatrix} + C_2 \begin{pmatrix} 2\sin t \\ \cos t - 3\sin t \end{pmatrix}$$

And

$$x_1(t) = 2C_1 \cos t + 2C_2 \sin t.$$

$$x_2(t) = (-3C_1 + C_2) \cos t + (-C_1 - 3C_2) \sin t$$

Permanent oscillations in both directions.



Center
stable.

For $\hat{x}(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$

$$\hat{x}'(0) = \begin{pmatrix} 3 & 2 \\ -5 & -3 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ -5 \end{pmatrix}$$

For $\hat{x}(0) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $\begin{pmatrix} 3 & 2 \\ -5 & -3 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -3 \end{pmatrix}$