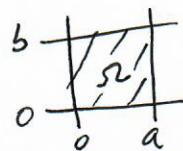


SOR Applied to Poisson's Equation.

BVP:
$$\begin{cases} \nabla^2 u = f(x, y), & (x, y) \in \Omega, \\ u(\vec{x}_s) = \gamma(\vec{x}_s), & \vec{x}_s \in \partial\Omega \end{cases}$$



Using 5-point stencil finite difference method
(2nd order centered fdm).

$$\boxed{\nabla_s^2 U_{jk} = f_{ij}} \quad (0.1)$$

$$\frac{U_{j+1,k} - 2U_{j,k} + U_{j-1,k}}{(\Delta x)^2} + \frac{U_{j,k+1} - 2U_{j,k} + U_{j,k-1}}{\Delta y^2} = f_{jk}$$

In matrix form: $\boxed{A\vec{U} = \vec{f}}$ $= f_{jk}$

Solving for U_{jk} , $j=1, \dots, N_x-1$, $k=1, \dots, N_y-1$ (1.1)

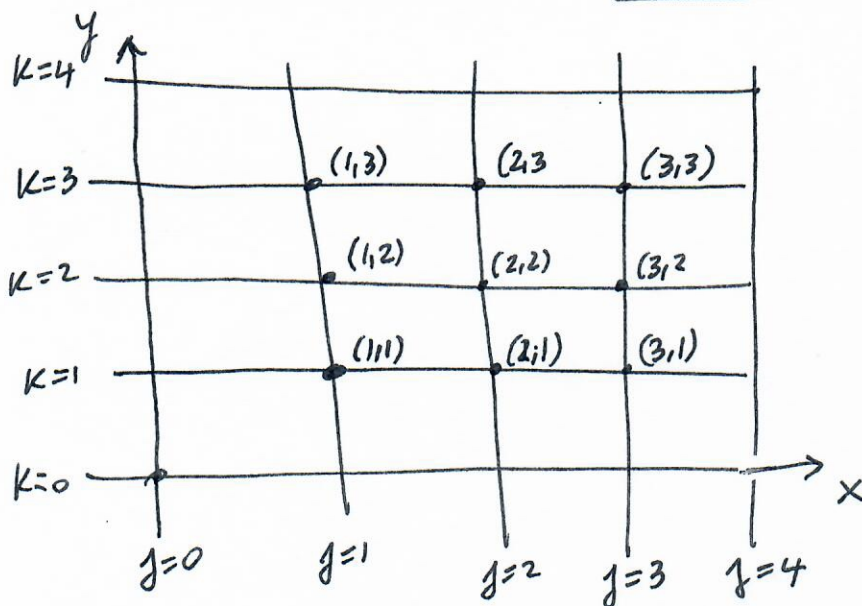
$$\boxed{U_{jk} = \theta_x (U_{j+1,k} + U_{j-1,k}) + \theta_y (U_{j,k+1} + U_{j,k-1}) - \theta_f f_{jk}}$$

Where $\theta_x = \frac{\Delta y^2}{2(\Delta x^2 + \Delta y^2)}$, $\theta_y = \frac{\Delta x^2}{2(\Delta x^2 + \Delta y^2)}$ (1.2)

and

$$\theta_f = \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)}$$

For $N_x = 4, N_y = 4$ DIRICHLET PROBLEM



$$\begin{array}{l}
 K=1 \quad \begin{pmatrix} -1 & \theta_x & 0 \\ \theta_x & -1 & \theta_x \\ 0 & \theta_x & -1 \end{pmatrix} \begin{pmatrix} \theta_y & 0 & 0 \\ 0 & \theta_y & 0 \\ 0 & 0 & \theta_y \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} j=1 \\ j=2 \\ j=3 \end{array} \quad \begin{pmatrix} v_{11} \\ v_{21} \\ v_{31} \end{pmatrix} \\
 A = \cdot \\
 K=2 \quad \begin{pmatrix} \theta_y & 0 & 0 \\ 0 & \theta_y & 0 \\ 0 & 0 & \theta_y \end{pmatrix} \begin{pmatrix} -1 & \theta_x & 0 \\ \theta_x & -1 & \theta_x \\ 0 & \theta_x & -1 \end{pmatrix} \begin{pmatrix} \theta_y & 0 & 0 \\ 0 & \theta_y & 0 \\ 0 & 0 & \theta_y \end{pmatrix} \quad \begin{array}{l} j=1 \\ j=2 \\ j=3 \end{array} \quad \begin{pmatrix} v_{12} \\ v_{22} \\ v_{32} \end{pmatrix} \\
 K=3 \quad \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \theta_y & 0 & 0 \\ 0 & \theta_y & 0 \\ 0 & 0 & \theta_y \end{pmatrix} \begin{pmatrix} -1 & \theta_x & 0 \\ \theta_x & -1 & \theta_x \\ 0 & \theta_x & -1 \end{pmatrix} \quad \begin{array}{l} j=1 \\ j=2 \\ j=3 \end{array} \quad \begin{pmatrix} v_{13} \\ v_{23} \\ v_{33} \end{pmatrix}
 \end{array}$$

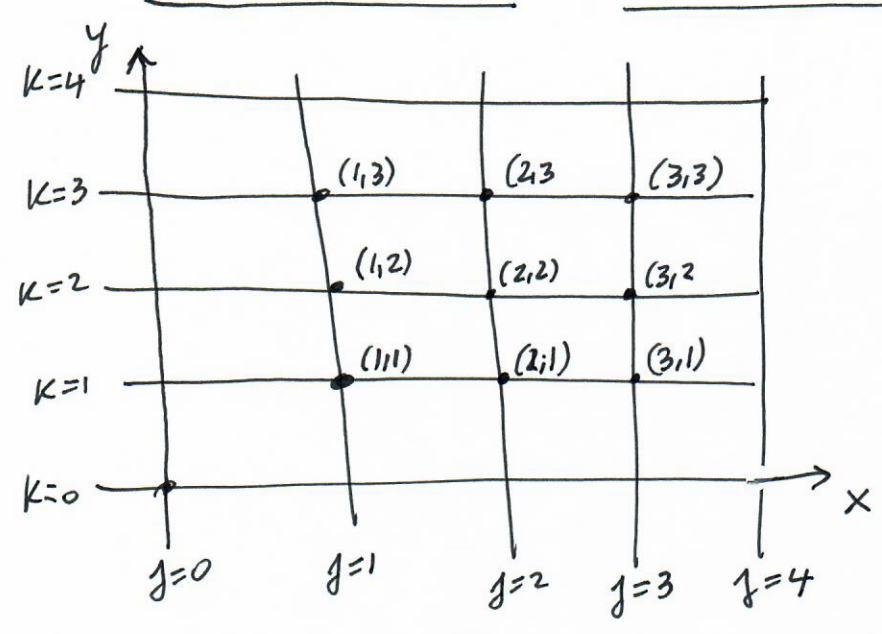
A

where

$$\vec{U} = \begin{bmatrix} U_{11} \\ U_{21} \\ \vdots \\ U_{N_x-1,1} \\ U_{12} \\ \vdots \\ U_{N_x-1,2} \\ \vdots \\ U_{1,N_y-1} \\ \vdots \\ U_{N_x-1,N_y-1} \end{bmatrix}$$

$$\vec{C} = -\theta_f \begin{bmatrix} f_{11} \\ \vdots \\ f_{N_x-1,1} \\ f_{12} \\ \vdots \\ f_{N_x-1,2} \\ \vdots \\ f_{1,N_y-1} \\ \vdots \\ f_{N_x-1,N_y-1} \end{bmatrix} \quad (9.1)$$

For $N_x = 4, N_y = 4$ DIRICHLET PROBLEM



(10.1)

$$M_{\substack{j \\ k}} = \begin{pmatrix} \begin{matrix} k=1 \\ \begin{pmatrix} 0 & \theta_x & 0 \\ \theta_x & 0 & \theta_x \\ 0 & \theta_x & 0 \end{pmatrix} \\ \end{matrix} & \begin{matrix} k=2 \\ \begin{pmatrix} \theta_y & 0 & 0 \\ 0 & \theta_y & 0 \\ 0 & 0 & \theta_y \end{pmatrix} \\ \end{matrix} & \begin{matrix} k=3 \\ \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \\ \end{matrix} \end{pmatrix} \begin{pmatrix} \begin{matrix} j=1 \\ \begin{pmatrix} \theta_y & 0 & 0 \\ 0 & \theta_y & 0 \\ 0 & 0 & \theta_y \end{pmatrix} \\ \end{matrix} & \begin{matrix} j=2 \\ \begin{pmatrix} 0 & \theta_x & 0 \\ \theta_x & 0 & \theta_x \\ 0 & \theta_x & 0 \end{pmatrix} \\ \end{matrix} & \begin{matrix} j=3 \\ \begin{pmatrix} \theta_y & 0 & 0 \\ 0 & \theta_y & 0 \\ 0 & 0 & \theta_y \end{pmatrix} \\ \end{matrix} \end{pmatrix} \begin{matrix} j=1 \\ j=2 \\ j=3 \end{matrix} \quad (10.2)$$

Iterative techniques:

$$K = 1, \dots, N_x - 1$$

$$J = 1, \dots, N_y - 1$$

a) Jacobi:

$$U_{JK}^{(l+1)} = \theta_x (U_{J+1,K}^{(l)} + U_{J-1,K}^{(l)}) + \theta_y (U_{J,K+1}^{(l)} + U_{J,K-1}^{(l)}) - \theta_f f_{JK} \quad (5.1)$$

b) Gauss-Seidel:

$$U_{JK}^{(l+1)} = \theta_x (U_{J+1,K}^{(l)} + U_{J-1,K}^{(l+1)}) + \theta_y (U_{J,K+1}^{(l)} + U_{J,K-1}^{(l+1)}) - \theta_f f_{JK} \quad (5.2)$$

c) SOR:

$$U_{JK}^{(l+1)} = \omega \left(U_{JK}^{(l+1)} \right)_{GS} + (1 - \omega) U_{JK}^{(l)} \quad (5.3)$$

In matrix form, as a fixed point problem:

$$\vec{U} = M_\omega \vec{U} + C_\omega$$

- Key questions:
- i) Conditions on original matrix A for converg.
 - ii) Appropriate range of ω for convergence.
 - iii) Finding optimum ω .
 - iv) Rate of convergence.

Summary

Finding the W_{opt} for SOR

Applied to Poisson equation.

(I) Poisson Equ. (2D): $u_{xx} + u_{yy} = f(x, y)$

(II) 5-point scheme:

$$\frac{u_{j,k+1} - 2u_{jk} + u_{j,k-1}}{(\Delta y)^2} + \frac{u_{j+1,k} - 2u_{jk} + u_{j-1,k}}{(\Delta x)^2} = f_{jk}$$

(III) Direct Scheme:

$$\theta_y u_{j,k-1} + \theta_x u_{k-1,j} - u_{jk} + \theta_x u_{k+1,j} + \theta_y u_{j,k+1} = \theta_f f_{jk}$$

where

$$\theta_y = \frac{(\Delta x)^2}{2(\Delta x^2 + \Delta y^2)}, \quad \theta_x = \frac{\Delta y^2}{2(\Delta x^2 + \Delta y^2)}, \quad \theta_f = \frac{\Delta x^2 \Delta y^2}{2(\Delta x^2 + \Delta y^2)}$$

(IV) Fixed-Point Problem:

$$u_{jk} = \theta_x (u_{j+1,k} + u_{j-1,k}) + \theta_y (u_{j,k+1} + u_{j,k-1}) - \theta_f f_{jk}$$

or

$$\vec{u} = M \vec{u} + \vec{C}$$

where M is defined as follows assuming $N_x = 4 = N_y$.

Three Possible Iterative Techniques.

$$(1) \quad \vec{U}^{(l+1)} = M_j \vec{U}^{(l)} + \vec{C}$$

$$(2) \quad \vec{U}^{(l+1)} = M_{gs} \vec{U}^{(l)} + \vec{C}_{gs}$$

$$(3) \quad \vec{U}^{(l+1)} = M_w \vec{U}^{(l)} + \vec{C}_s$$

(Kahan)

(V) Range of ω : If $a_{ii} \neq 0$ (which is our case $a_{ii} = 1$)
Poisson's Equ.

then If SOR converges $\Rightarrow 0 < \omega < 2$.

(VI) Convergence SOR:

$$\vec{U}^{(k)} = M_{\omega} \vec{U}^{(k-1)} + \vec{C}_{\omega} \text{ converges to } \vec{U}^*$$

fixed point of $\vec{U} = M_{\omega} \vec{U} + \vec{C}$. for $0 < \omega < 2$
and for any initial guess.

(VII) ω optimum of SOR and spectral radius $\rho(M_{\omega_{opt}})$.

$$\omega_{opt} = \frac{2}{1 + \sqrt{1 - \rho^2(M_j)}}$$

and

$$\rho(M_{\omega_{opt}}) = \omega_{opt} - 1$$

(VIII) Comparison of spectral radius

$$\rho(M_j) \approx 1 - \frac{\pi^2}{2N_x^2}$$

$$\rho(M_g) \approx 1 - \frac{\pi^2}{N_x^2}$$

$$\rho(M_{\omega_{opt}}) \approx 1 - \frac{\pi}{N_x}$$

Computation of $\rho(M_j)$

(IX) Eigenvalues of M_j

$$\mu_{mn} = 1 - 4\theta_x \sin^2\left(\frac{m\pi}{2N_x}\right) - 4\theta_y \sin^2\left(\frac{n\pi}{2N_y}\right)$$

$$m=1, \dots, N_x-1$$

$$n=1, \dots, N_y-1$$

If $N_x = N_y$, $\Delta x = \Delta y$.

$$\mu_{mn} = 1 - \sin^2\left(\frac{m\pi}{2N_x}\right) - \sin^2\left(\frac{n\pi}{2N_x}\right)$$

(X) Largest Eigenvalue: When $m=n=1$

$$\mu_{1,1} = 1 - 2 \sin^2\left(\frac{\pi}{2N_x}\right)$$

Wopt when $\Delta x = \Delta y$ but $N_x \neq N_y$

$$\rho(M_j) = 1 - \sin^2 \frac{\pi}{2N_x} - \sin^2 \frac{\pi}{2N_y} = \frac{1}{2} \left(\cos \frac{\pi}{N_x} + \cos \frac{\pi}{N_y} \right)$$

and

$$W_{\text{opt}} = \frac{2}{1 + \sqrt{1 - \rho^2(n_j)}} = \frac{2}{1 + \sqrt{1 - \frac{1}{4} \left(\cos \frac{\pi}{N_x} + \cos \frac{\pi}{N_y} \right)^2}}$$

or

$$W_{\text{opt}} = \frac{4}{2 + \sqrt{4 - \left(\cos \frac{n\pi}{N_x} + \cos \left(\frac{\pi}{N_y} \right)^2 \right) d_s}}$$