

Convergence Theorems

Consider a finite difference method given by

$$\boxed{A \vec{U} = \vec{f}}, \quad A_{m \times m} \text{ matrix.} \quad (1)$$

Splitting the matrix A as

$$A = B - E, \quad B, E \text{ } m \times m \text{ matrices.} \quad (2)$$

System (1) can be written as

$$B \vec{U} = E \vec{U} + \vec{f}$$

If B is invertible then,

$$\vec{U} = B^{-1} E \vec{U} + B^{-1} \vec{f}$$

or

$$\boxed{\vec{U} = M \vec{U} + \vec{C}} \quad (3)$$

Where $M = B^{-1} E$ and $\vec{C} = B^{-1} \vec{f}$.

A natural iterative method can be defined from (3) as

$$\boxed{\vec{U}^{(k+1)} = M \vec{U}^{(k)} + \vec{C}}, \quad k = 1, 2, \dots \quad (4)$$

So starting with an initial guess $\vec{v}_0$,
 we generate a sequence $\{\vec{v}^{(k)}\}_{k=1}^{\infty}$ using (4).

If B is invertible then the linear systems

$$A\vec{v} = \vec{f} \quad \text{and} \quad \vec{v} = M\vec{v} + \vec{c}$$

are equivalent, i.e.,

$\vec{v}^*$ is a solution of (3)

$$\boxed{A\vec{v}^* = \vec{f}}$$

if and only if $\vec{v}^*$ is a fixed point of (4)

$$\boxed{\vec{v}^* = M\vec{v}^* + \vec{c}}$$

We have already found a sufficient condition for the convergence of (4) when $k \rightarrow \infty$ to a fixed point $\vec{v}^*$ of (3).

If $\|M\| < 1$, then the sequence $\{\vec{v}^{(k)}\}_1^{\infty}$ of iterative method converges to the fixed point $\vec{v}^*$ of (4).

Convergent Matrices

In studying iterative matrix techniques, it is of particular importance to know when a matrix becomes small (that is, when all the entries approach zero). Matrices of this type are called *convergent*.

Definition 7.16 We call an $n \times n$ matrix A **convergent** if

$$\lim_{k \rightarrow \infty} (A^k)_{ij} = 0, \quad \text{for each } i = 1, 2, \dots, n \text{ and } j = 1, 2, \dots, n.$$

Example 4 Show that

$$A = \begin{bmatrix} \frac{1}{2} & 0 \\ \frac{1}{4} & \frac{1}{2} \end{bmatrix}$$

is a convergent matrix.

Solution Computing powers of A , we obtain:

$$A^2 = \begin{bmatrix} \frac{1}{4} & 0 \\ \frac{1}{4} & \frac{1}{4} \end{bmatrix}, \quad A^3 = \begin{bmatrix} \frac{1}{8} & 0 \\ \frac{3}{16} & \frac{1}{8} \end{bmatrix}, \quad A^4 = \begin{bmatrix} \frac{1}{16} & 0 \\ \frac{1}{8} & \frac{1}{16} \end{bmatrix},$$

and, in general,

$$A^k = \begin{bmatrix} (\frac{1}{2})^k & 0 \\ \frac{k}{2^{k+1}} & (\frac{1}{2})^k \end{bmatrix}.$$

So A is a convergent matrix because

$$\lim_{k \rightarrow \infty} \left(\frac{1}{2}\right)^k = 0 \quad \text{and} \quad \lim_{k \rightarrow \infty} \frac{k}{2^{k+1}} = 0.$$

Notice that the convergent matrix A in Example 4 has $\rho(A) = \frac{1}{2}$, because $\frac{1}{2}$ is the eigenvalue of A . This illustrates an important connection that exists between the spectral radius of a matrix and the convergence of the matrix, as detailed in the following result.

7.2 Eigenvalues and Eigenvectors

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Theorem 7.17 The following statements are equivalent.

- (i) A is a convergent matrix.
- (ii) $\lim_{n \rightarrow \infty} \|A^n\| = 0$, for some natural norm.
- (iii) $\lim_{n \rightarrow \infty} \|A^n\| = 0$, for all natural norms.
- (iv) $\rho(A) < 1$.
- (v) $\lim_{n \rightarrow \infty} A^n \mathbf{x} = \mathbf{0}$, for every $\mathbf{x}$.

The proof of this theorem can be found in [IK], p. 14.

EXERCISE SET 7.2

1. Compute the eigenvalues and associated eigenvectors of the following matrices.

a. $\begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$

b. $\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$

c. $\begin{bmatrix} 0 & \frac{1}{2} \\ \frac{1}{2} & 0 \end{bmatrix}$

d. $\begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

e. $\begin{bmatrix} -1 & 2 & 0 \\ 0 & 3 & 4 \\ 0 & 0 & 7 \end{bmatrix}$

f. $\begin{bmatrix} 2 & 1 & 1 \\ 2 & 3 & 2 \\ 1 & 1 & 2 \end{bmatrix}$

2. Compute the eigenvalues and associated eigenvectors of the following matrices.

Lemma.

If $\rho(M) < 1$ then

i) $(I-M)^{-1}$ exists.

$$\text{ii) } (I-M)^{-1} = I + M + M^2 + \dots = \sum_{j=0}^{\infty} M^j$$

Proof.

i) First notice that $\rho(M) < 1$ implies

$\lambda = 1$ is not an eigenvalue of M . (*)

Now, we will show that $\mu = 0$ is not an eigenvalue of $I-M$.

In fact,

$\vec{x} \neq 0$ is an eigenvector of $I-M$

$\Leftrightarrow$ There is $\mu \in \mathbb{C}$ such that

$$(I-M)\vec{x} = \mu\vec{x} \Leftrightarrow M\vec{x} = (1-\mu)\vec{x}$$

But, from (*) $1-\mu \neq 1 \Leftrightarrow \mu \neq 0$

and as a consequence $(I-M)^{-1}$ exists.

ii) Call

$$S_m = I + M + \dots + M^m$$

then $MS_m = M + M^2 + \dots + M^{m+1}$

Thus,

$$(I - M)S_m = S_m - MS_m = I - M^{m+1}$$

and

$$(I - M) \lim_{m \rightarrow \infty} S_m = \lim_{m \rightarrow \infty} (I - M^{m+1}) = I - \lim_{m \rightarrow \infty} M^{m+1}$$

$\begin{array}{c} \text{Prev.} \\ \text{Theor} \\ \text{B-F.} \end{array} \quad \underline{= I}$

Therefore,

$$(I - M) \lim_{m \rightarrow \infty} S_m = I$$

or

$$(I - M)^{-1} = \sum_{j=0}^{\infty} M^j$$

A more useful condition can be given in terms of the spectral radius $\rho(M)$.

Theorem. 1.

If the spectral radius $\rho(M) < 1$ then, the fixed point problem $\vec{u} = M\vec{u} + \vec{c}$ has a unique solution for any $\vec{c}$.

Proof. -

If $\rho(M) < 1$, then $\lambda = 1$ is not an eigenvalue of M or there is not any $\vec{v} \neq \vec{0}$ such that

$$M\vec{v} = \vec{v}$$

This is equivalent to say, that there is not any $\vec{v} \neq \vec{0}$ such that

$$(I - M)\vec{v} = \vec{v} - M\vec{v} = \vec{0}$$

Therefore, $I - M$ is invertible

$$\text{and } (I - M)\vec{v} = \vec{c}$$

has a unique solution $\vec{v}^*$ for any $\vec{c}$

$$(I - M)\vec{v}^* = \vec{c} \Leftrightarrow \vec{v}^* = M\vec{v}^* + \vec{c}$$

which is equivalent to say that

$\vec{v} = M\vec{v} + \vec{c}$ has a unique fixed point $\vec{v}^*$ for any $\vec{c}$.

Theorem 2.

For any arbitrary vector $\vec{v}^0 \in \mathbb{R}^n$

the sequence $\{\vec{v}^{(k)}\}_{k=1}^{\infty}$ defined by

$$\vec{v}^{(k)} = M \vec{v}^{(k-1)} + \vec{c}, \quad k \geq 1$$

Converges to the unique solution $\vec{v}^*$ of (fixed point)

$$\vec{v} = M\vec{v} + \vec{c}$$

if and only if $\rho(M) < 1$.

Proof:-

For the proof we need these results:

a) $\rho(M) < 1 \Leftrightarrow \lim_{k \rightarrow \infty} M^k \vec{v} = \vec{0}$, for any $\vec{v}$.

b) $\rho(M) < 1 \xRightarrow{\text{lemma}} (I - M)^{-1} = I + M + M^2 + \dots = \sum_{j=0}^{\infty} M^j$

c) $\rho^k(M) \leq \|M^k\|$

d) Theorem 1: $\rho(M) < 1 \Rightarrow (I - M)$ is invertible
 $\Rightarrow (I - M)^{-1}$ is invertible.

Then, for any $\vec{c}$, there exists a unique soln. $\vec{v}^*$ such that
 $(I - M)\vec{v}^* = \vec{c} \Leftrightarrow (I - M)^{-1}\vec{c} = \vec{v}^*$.

$$\rho(M) < 1 \Leftrightarrow \lim_{k \rightarrow \infty} M^k = [0]$$

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A particular case

If M is diagonalizable

$$M = P^{-1} D P$$

$$P = \begin{pmatrix} \hat{v}_1 & \dots & \hat{v}_n \\ \downarrow & & \downarrow \end{pmatrix} \text{ eigenvectors}$$

$$D = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} \text{ eigenvalues.}$$

$$M^k = P^{-1} D^k P$$

$$D^k = \begin{pmatrix} \lambda_1^k & & \\ & \ddots & \\ & & \lambda_n^k \end{pmatrix}$$

$$\rho(M) < 1 \Leftrightarrow |\lambda_i| < 1, \quad i=1, \dots, n$$

$$\Leftrightarrow \lim_{k \rightarrow \infty} D^k \rightarrow [0] \quad \Leftrightarrow \lim_{k \rightarrow \infty} M^k \rightarrow [0]$$

Proof. ($\Rightarrow$) Convergence $\Rightarrow \rho(M) < 1$

Let $\vec{v}^*$ be the unique soln. of

$$\vec{v} = M\vec{v} + \vec{c}. \quad \text{It means} \quad (6.1)$$

$$\text{and } \vec{v}^k \rightarrow \vec{v}^*, \text{ where } \vec{v}^{(k)} = M\vec{v}^{(k-1)} + \vec{c} \quad (6.2)$$

Then, Subtracting (6.1) from (6.2).

$$\begin{aligned} \vec{e}^k = \vec{v}^{(k)} - \vec{v}^* &= M(\vec{v}^{(k-1)} - \vec{v}^*) = M\vec{e}^{(k-1)} \\ &= M(M\vec{e}^{(k-2)}) = M^2\vec{e}^{(k-2)} = \dots = M^k\vec{e}^0 \end{aligned}$$

Therefore,

$$\|M^k\vec{e}^0\| = \|\vec{e}^k\| = \|\vec{v}^{(k)} - \vec{v}^*\| \xrightarrow[k \rightarrow \infty]{\text{Hip}} 0$$

Since $\vec{e}^0 = \vec{v}^{(0)} - \vec{v}^*$ and $\vec{v}^{(0)}$ is arbitrary

$$\|M^k\| = \max_{\|\vec{x}\| \neq 0} \frac{\|M^k \vec{x}\|}{\|\vec{x}\|} \xrightarrow[k \rightarrow \infty]{} 0 \quad \xRightarrow[\text{B-F Thm 7.17}]{\text{Hip}} \lim_{k \rightarrow \infty} \|M^k\| = 0$$

Therefore,

$$\rho^{(k)}(M) = \rho(M^k) \leq \|M^k\| \xrightarrow[k \rightarrow \infty]{} 0$$

$$\Rightarrow \rho(M) < 1$$

($\Leftarrow$) $\rho(M) < 1 \Rightarrow \text{Convergence}$

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$$\begin{aligned}\vec{U}^{(k)} &= M \vec{U}^{(k-1)} + \vec{C} = M(M \vec{U}^{(k-2)} + \vec{C}) + \vec{C} \\ &= M^2 \vec{U}^{(k-2)} + M\vec{C} + \vec{C} \\ &\vdots \\ &= M^k \vec{U}^0 + \left(\sum_{j=0}^{k-1} M^j \right) \vec{C} \\ &\quad \downarrow \text{(a)} \quad \downarrow \text{(b) lemma} \\ &\quad 0 \quad (I-M)^{-1} \vec{C}\end{aligned}$$

$$\therefore \lim_{k \rightarrow \infty} \vec{U}^{(k)} = (I-M)^{-1} \vec{C} \stackrel{(d)}{=} \vec{U}^*$$

Assuming that

$$M = B^{-1}E \text{ and } A = B - E, \text{ and } \vec{C} = B^{-1}\vec{f}.$$

then $\vec{U}^*$ is also the solution of

$$A\vec{U} = \vec{f}.$$

In fact, if $\vec{U}^* = M\vec{U}^* + \vec{C}$

$$\text{Then, } \vec{U}^* = (B^{-1}E)\vec{U}^* + \vec{C}$$

$$\Rightarrow B\vec{U}^* = E\vec{U}^* + B\vec{C} = E\vec{U}^* + B(B^{-1}\vec{f})$$

$$\Rightarrow (B-E)\vec{U}^* = \vec{f} \Rightarrow A\vec{U}^* = \vec{f}.$$

Ideas for proofs of lemma and theorem

Lemma

$$\rho(M) < 1 \Rightarrow (I - M)^{-1} \text{ exists}$$

i) $\lambda = 1$ not an eigenvalue $\Rightarrow \mu = 0$ not an eigenv. of $I - M$.

ii) Similar to geometric sequence proof of converg.

$$\sum_{n=0}^{\infty} r^n = \frac{1}{1-r}$$

Thm 2
($\rightarrow$) Converg $\Rightarrow \rho(M) < 1$ $\rightarrow \|\tilde{U}^k - \tilde{U}\| \xrightarrow{k \rightarrow \infty} 0$ HIP

$$\rho^k(M) \leq \|M^k\| \rightarrow 0 \Rightarrow \rho(M) < 1$$

and $\|M^k\| \rightarrow 0$ Since $\|M^k \tilde{e}_0\| \rightarrow 0$ for any $\tilde{e}_0$.

($\leftarrow$) Prove directly

$$\tilde{U}^{(k)} \rightarrow \tilde{U}^*$$

Just developing $\tilde{U}^{(k)} = M \tilde{U}^{(k-1)} + \tilde{C} = \dots$

Alternative: $\rho(M) < 1 \Rightarrow$ there exists U^* s.t.

$$U^* = M U^* + \tilde{C} \text{ unique solu.}$$

$$(2) \|M^k\| \xrightarrow{k \rightarrow \infty} 0$$

$$\Rightarrow \|\tilde{U}^{(k)} - U^*\| = \|\tilde{e}^k\| = \dots = \|M^k \tilde{e}^{(0)}\| \leq \|M^k\| \|\tilde{e}^{(0)}\| \xrightarrow{k \rightarrow \infty} 0$$

$\downarrow \rho(M) < 1$
0

Thm A is S.D.D. $\Rightarrow A$ is nonsingular.

Proof.

If A is singular then there is $\vec{x} \neq \vec{0}$

S.t. $A\vec{x} = \vec{0}$.

Say $0 < |x_k| = \max_{1 \leq j \leq n} |x_j|$

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{k1} & a_{k2} & \dots & a_{kn} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_k \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

From Hypothesis $\sum_{j=1}^n a_{kj} x_j = 0 \Rightarrow a_{kk} x_k = - \sum_{j \neq k} a_{kj} x_j$

$$\Rightarrow |a_{kk}| |x_k| \leq \sum_{j \neq k} |a_{kj}| |x_j|$$

$$\Rightarrow |a_{kk}| \leq \sum_{j \neq k} |a_{kj}| \frac{|x_j|}{|x_k|} \leq \sum_{j \neq k} |a_{kj}|$$

not S.D.D.

Consider $A\vec{u} = \vec{f}$ (0.1)

And a decomposition of A (splitting)

$$A = B - E.$$

Theorem. If B is invertible

$A\vec{u} = \vec{f}$ is equivalent to $\vec{u} = M\vec{u} + \vec{c}$
where $M = B^{-1}E$, $\vec{c} = B^{-1}\vec{f}$

Proof.

$$A\vec{u} = \vec{f} \Leftrightarrow (B - E)\vec{u} = \vec{f}$$

$$\Leftrightarrow B\vec{u} = E\vec{u} + \vec{f}$$

$$\Leftrightarrow \vec{u} = B^{-1}(E\vec{u}) + B^{-1}\vec{f}$$

$$\Leftrightarrow \vec{u} = M\vec{u} + \vec{c}$$

Corollary.

If A is S.D.D., then

- The diagonal matrix D corresponding to A is invertible
- $A\vec{u} = \vec{f}$ is equivalent to $\vec{u} = M_j \vec{u} + \vec{c}$ (M_j is Jacobi matrix)
- $\vec{u} = M_j \vec{u} + \vec{c}$ has a unique soln. $M_j = D^{-1}(L_T + U_T)$

Proof.

If A is S.D.D.

then

$$D = \begin{pmatrix} a_{11} & \dots & 0 \\ 0 & a_{22} & \\ \vdots & & \ddots \\ 0 & & & a_{nn} \end{pmatrix} \text{ is nonsingular}$$

Since $a_{kk} \neq 0$, for all k .

Then, according to previous theorem

$$A\vec{u} = \vec{f} \text{ is equivalent to } \vec{u} = M_j \vec{u} + \vec{c}$$

Also, $A\vec{u} = \vec{f}$ has a unique solution $\vec{u}^*$,

according to another previous theorem. in page 1.

As a consequence,

$\vec{u}^*$ is also the unique soln (fixed point)

of $\vec{u} = M_j \vec{u} + \vec{c}$, or

$$\vec{u}^* = M_j \vec{u}^* + \vec{c}.$$

Theorem. A is S.D.D $\Rightarrow \vec{v}^{(k)} = M_j \vec{v}^{(k-1)} + \vec{c}$

Converges to the unique soln. $\vec{v}^*$ of

$$\vec{v} = M_j \vec{v} + \vec{c} \text{ in the } \|\cdot\|_{\infty} \text{ norm.}$$

Proof. It's enough to prove that $\|M_j\|_{\infty} < 1$

In fact,

$$M_j = \begin{pmatrix} 0 & -a_{12}/a_{11} & \dots & -a_{1n}/a_{11} \\ -a_{21}/a_{22} & 0 & \dots & -a_{2n}/a_{22} \\ \vdots & \vdots & \ddots & \vdots \\ -a_{n1}/a_{nn} & \dots & -\frac{a_{nn-1}}{a_{nn}} & 0 \end{pmatrix} = D^{-1}(L_T + U_T)$$

Then,

$$\|M_j\|_{\infty} = \max_{1 \leq i \leq n} \sum_{\substack{j=1 \\ j \neq i}}^n \left| -\frac{a_{ij}}{a_{ii}} \right| = \max_{1 \leq i \leq n} \sum_{\substack{j=1 \\ j \neq i}}^n \frac{|a_{ij}|}{|a_{ii}|}$$

$$= \max_{1 \leq i \leq n} \frac{1}{|a_{ii}|} \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}| < \overset{\text{H.P. S.D.D.}}{1}$$

Application to our example,

$$\begin{pmatrix} 2 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 8 \\ -5 \end{pmatrix}$$

$$\underset{\text{S.D.D.}}{A} \quad \vec{x} = \vec{b}$$

Jacobi's method leads to

$$\begin{pmatrix} 0 & 1/2 & 0 \\ 1/3 & 0 & 1/3 \\ 0 & 1/2 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1/2 \\ 8/3 \\ -5/2 \end{pmatrix}$$

$$M_J \quad \vec{x} = \vec{c}$$

Then,

$$\|M_J\| = \max_{1 \leq i \leq 3} \left(\sum_{j=1}^3 |a_{ij}| \right) = \frac{2}{3} < 1$$

Therefore, Jacobi's method converges.